

Determining Spatial Resolution from Brain Imaging for Automated Quality Assurance of Magnetic Resonance Imaging

Liam S. P. Lawrence, PhD¹; Brige P. Chugh, PhD^{1,2}; Jay Detsky, MD, PhD¹; Arjun Sahgal, MD¹; Angus Z. Lau, PhD^{1,3}
¹Sunnybrook Health Sciences Centre, ²Toronto Metropolitan University, ³University of Toronto

INTRODUCTION

- Current recommendation from TG-284 for MRI quality assurance (QA): Evaluate image quality metrics from phantom scans (1).
- Phantom-based QA has limitations:
 - Clinical imaging sequences are not tested during QA.
 - Phantom-based QA requires staff time for scanning phantoms.
- The limitations of phantom-based QA could be solved by evaluating QA metrics directly from patient imaging.**
- This strategy requires developing techniques to measure image quality metrics from *in vivo* MRI (2).
- This abstract: An automated approach to estimate spatial resolution in brain MRI.

METHODS AND MATERIALS

Algorithm

- Intensities over an image patch containing the genu-ventricle interface were projected onto an axis perpendicular to the edge (**Figure 1**).
- The theoretical edge-spread function was fitted to the profile (3).
- To account for systematic errors that create positive bias, the minimum spatial resolution estimate across many patches defined algorithmically was chosen (**Figure 2**).
- The resolution was assumed to be isotropic in-plane.

Cohort (N=30)

- Central nervous system tumour patients
- Scans:
 - 1.5T Unity MR-Linac (N=15)
 - 0.5 T Synaptive Evry (N=5)
 - 1.5 T Philips Ingenia (N=5)
 - 3 T Philips Achieva (N=5)
- T1-weighted, diffusion-weighted, and multi-echo spin echo imaging with voxel sizes ranging from 1.0-3.0 mm.
- Repeatability measured from MRL scans.

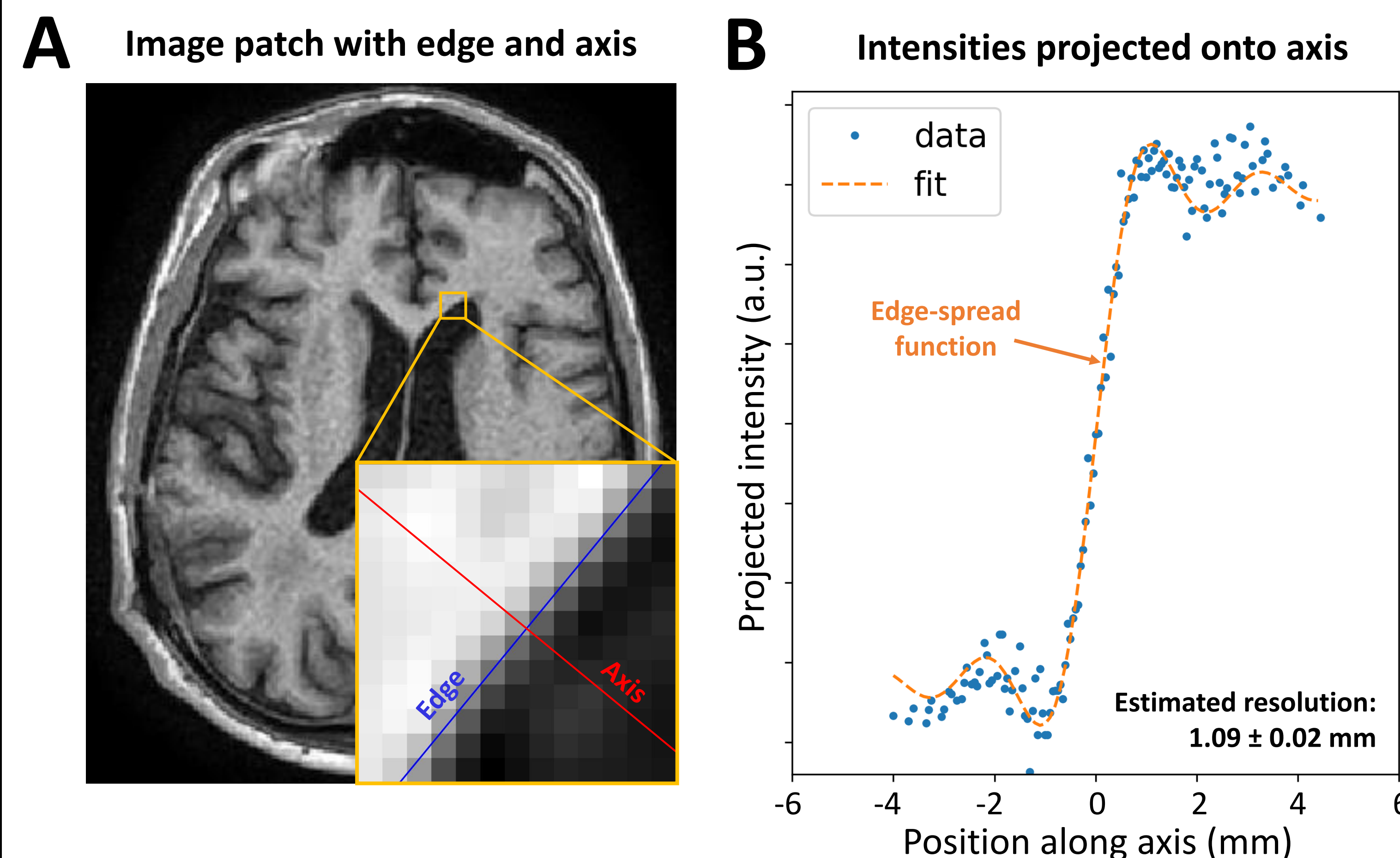


Figure 1 – Spatial resolution measurement from (A) an automatically selected image patch and (B) the resulting model fit and resolution estimate.

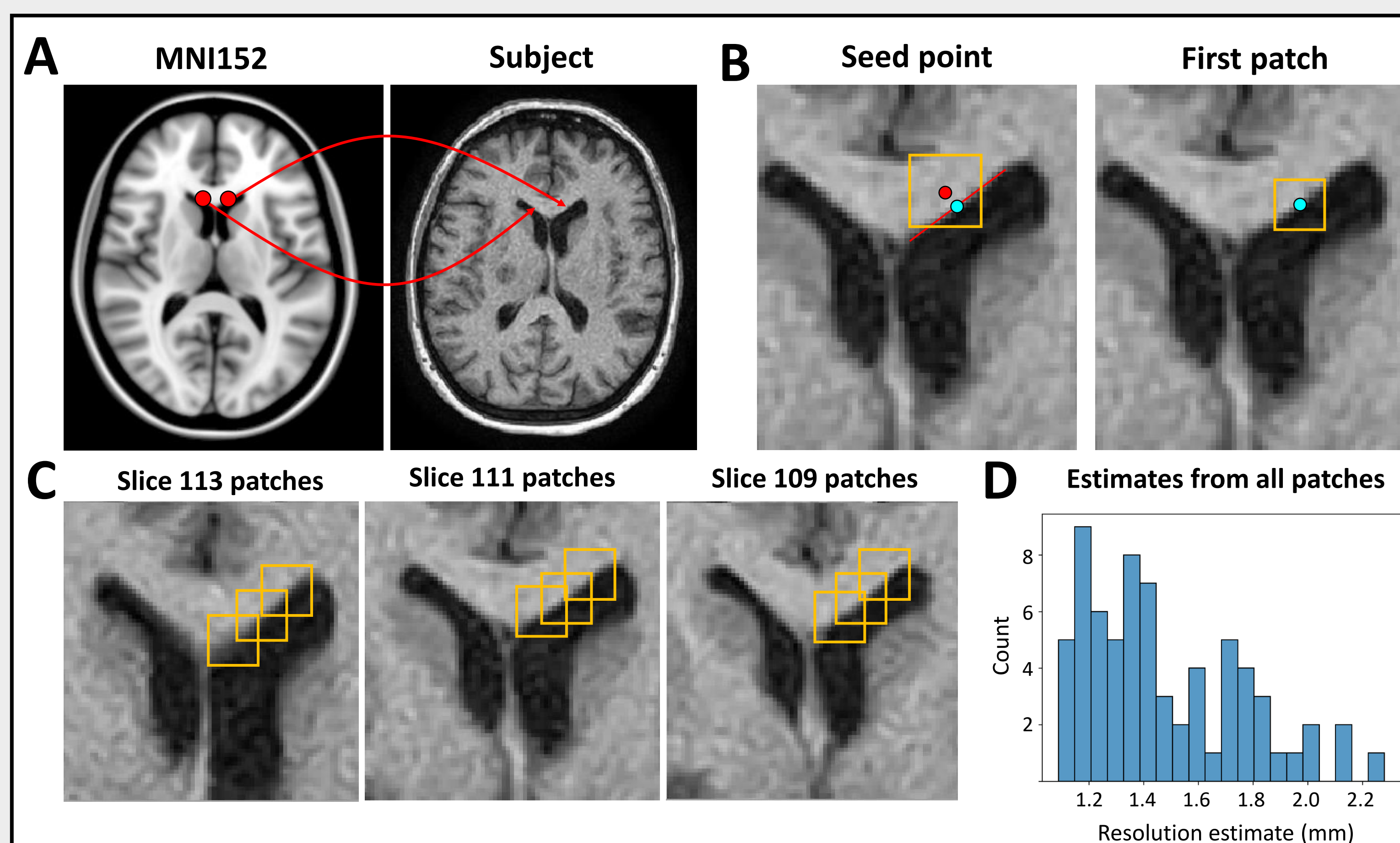


Figure 2 – Algorithm for automatic spatial resolution estimation. (A) Seed points from MNI152 space are (B) snapped to the edge to create the first patch. (C) Additional patches are created by translation in-plane and cross-plane. (D) The minimum estimate across all patches is chosen as the definitive measurement.

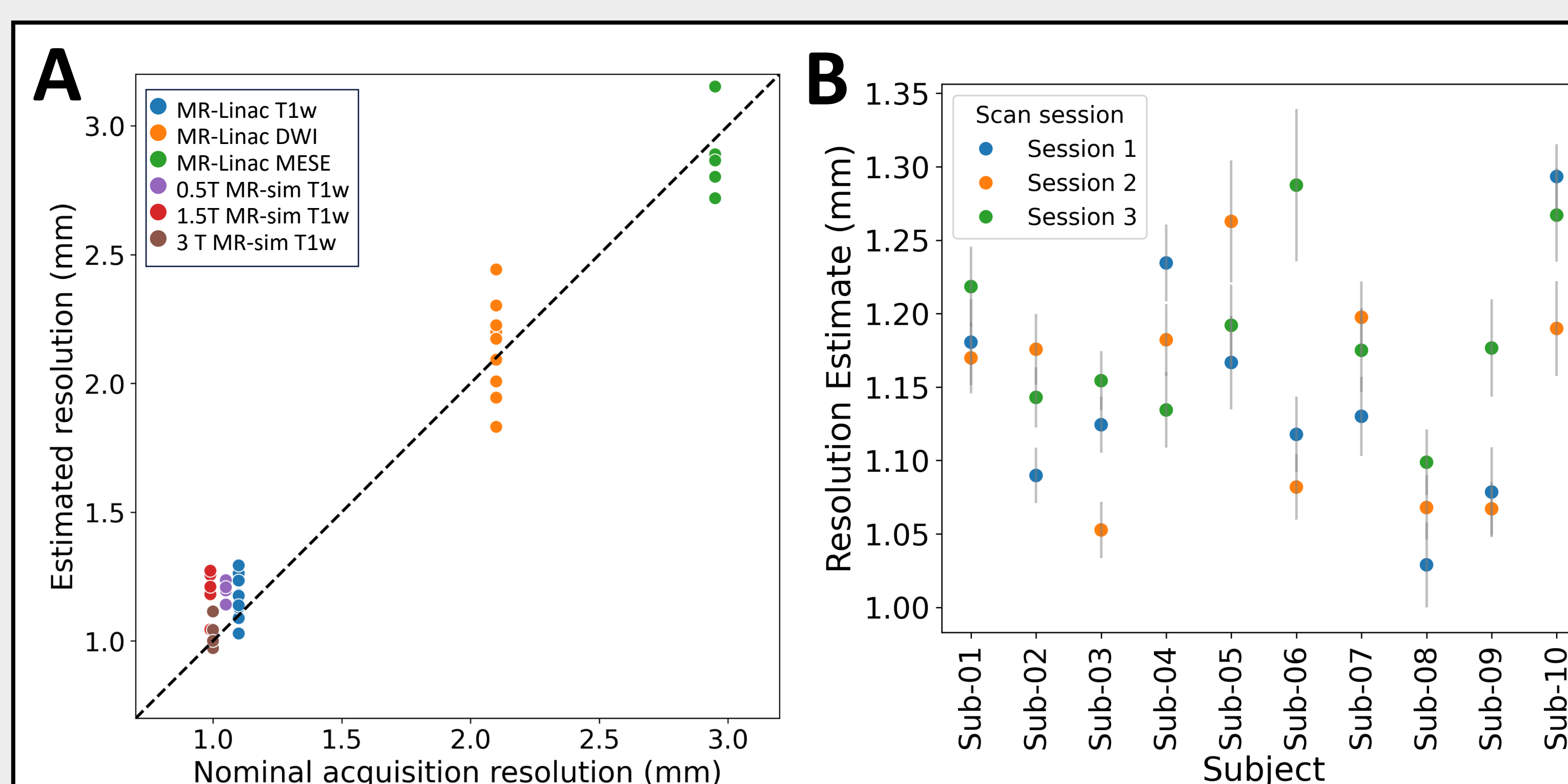


Figure 3 – Spatial resolution measurement accuracy and repeatability. (A): Measured versus nominal resolution. (B): Repeated measurements from 10 subjects show that a resolution change of 0.15 mm is detectable.

RESULTS

- The estimated resolution per protocol, averaged across subjects, was within 0.1-0.2 mm of the nominal resolution (**Table 1**).
- The individual estimated and nominal resolutions showed strong correlation ($r=0.98$, $p<.001$) (**Figure 3A**).
- The within-subject standard deviation was 0.056 mm, corresponding to a repeatability coefficient of 0.15 mm (**Figure 3B**) (cf. tolerance of 0.1 mm, AAPM Report 100).

Table 1 – Comparison of nominal resolution to measured resolution. The resolution measurement assumes isotropic voxels, so only a 1D value is shown.

Sequence	Nominal resolution (mm ²)	Measured resolution (mm)
MRL T1w	1.1×1.1	1.17 ± 0.08
MRL DWI	2.0×2.2	2.2 ± 0.2
MRL MESE	3.0×2.9	2.9 ± 0.2
0.5 T T1w	1.1×1.0	1.20 ± 0.03
1.5 T T1w	0.98×1.0	1.19 ± 0.09
3.0 T T1w	1.0×1.0	1.02 ± 0.06

DISCUSSION AND CONCLUSIONS

- First report of direct estimation of spatial resolution of MRI *in vivo*.**
- Strengths: Automated, applicable to clinically-acquired sequences.
- Limitations: Only developed for brain MRI, isotropic voxel sizes assumed.
- Future work: Extend the method to anisotropic spatial resolution.
- Potential applications in patient-specific QA from high-volume machines like MRI-linacs.

REFERENCES

- C. K. Glide-Hurst *et al.*, *Med. Phys.* **48** (2021), doi:10.1002/mp.14695.
- O. Esteban *et al.*, *PLoS One*. **12** (2017), doi:10.1371/journal.pone.0184661.
- I. Delakis, C. Xanthis, R. I. Kitney, *Med. Phys.* **36**, 1637–1642 (2009).

CONTACT

Liam Lawrence: liam.lawrence@sunnybrook.ca
Angus Lau: angus1.lau@sunnybrook.ca